

TOWARDS THE MODELING OF GLACIER MICROTOPOGRAPHY USING HIGH-RESOLUTION DATA FROM UNMANNED AERIAL SURVEY

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ABSTRACT:

Glaciated areas are important targets for interdisciplinary research. In the last quarter of the 20th century, there has been a significant shift in glacier observation approaches from direct fieldwork to remote sensing. Over the past 15 years, unmanned aerial systems have been increasingly used for this purpose. In this article, we briefly describe a newly launched Russian–Chinese project aimed at developing a theory and methodology for digital modeling and analysis of the glacier microtopography using very high resolution data from unmanned aerial surveys. We argue the relevance of the study and review key publications on the application of digital terrain modeling and geomorphometry in glaciology. Next, we discuss the aim of the project and tasks performed by the Russian side, as well as materials and methods used in the study. As initial data, we use multi-temporal, digital aerial images of very high resolution (5 cm) collected by the unmanned aerial survey of the ice sheet and glaciers near the Larsemann Hills, East Antarctic. Finally, we present some examples for geomorphometric analysis of glacier microtopography including snow/ice features of eolian origin.

1. INTRODUCTION

Glaciated areas are important targets for interdisciplinary research. This is due to a number of political, economic, and scientific factors.

First, one of the core political tasks of the Russian Government is to ensure the development of the Arctic territories, which are a zone of Russia's strategic interests. An equally important geopolitical goal is to ensure the Russian presence in the Antarctic region. In addition, access to fresh water sources, including glaciers, gradually becomes a serious tool of various political actors, especially in arid zones of Central Asia.

Second, glaciated areas have a significant impact on climate change at the global and regional scales. On the other hand, glacier dynamics is an indirect indicator of regional climate changes.

Third, glaciers are in continuous motion leading to constant changes in the geometry of glacial topography at different spatial scales (from macro- to microtopography). Such changes can be both slow and catastrophic. In particular, dangerous crevasses and subsidences are formed in glacier surfaces. Some natural processes in glaciers and ice sheets (e.g., outbursts of water from glacier lakes) can lead to catastrophic consequences in the adjacent valleys. In this regard, safety studies, prompt monitoring, and mathematical modeling of glaciers are important.

In the last quarter of the 20th century, there has been a significant shift in glacier observation approaches from direct

fieldwork to remote sensing. Over the past 15 years, unmanned aerial systems (UASs) have been increasingly used for this purpose. In particular, one of the most promising approaches for studying glaciers is their mathematical modeling and simulation using digital elevation models (DEMs) of high and ultra-high resolution produced from UAS-based data.

2. DIGITAL TERRAIN MODELING IN GLACIOLOGY: A SHORT REVIEW

2.1 Achievements

The application of digital terrain modeling in glaciology began in the 1990s. Suetova and Chistov (1993) created small-scale DEMs for portions of Antarctica using cartographic materials. Etzelmüller and Sollid (1997) introduced a concept of glacial geomorphometry and created a series of DEMs for Svalbard using multi-temporal aerial images. Later on, researchers used medium- and small-scale DEMs of individual glaciers, their portions, and the whole of Antarctica and Greenland. Such DEMs – with resolutions of meters as well as tens and hundreds of meters – are usually created from topographic maps, aerial and satellite imagery, as well as ground topographic and lidar data. These DEMs are used to assess and study the dynamics of glaciers and snow fields, their volumes, and so on (Pogorelov, 1999; Etzelmüller, 2000; Knizhnikov et al., 2000, 2002; Rippin et al., 2003; DiMarzio et al., 2005; Racoviteanu et al., 2007; Fox, Cziferszky, 2008; Käab, 2008; Zolotarev, 2009; Bamber et al., 2009; Bhabri, Bolch, 2009; Boyko, 2010; Fretwell et al., 2013; Helm et al., 2014; Semakova, Semakov, 2017). The low resolution of such DEMs imposes serious limitations on the ability to study and model glacial processes.

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Unmanned aerial survey of glaciers was initiated by Hodson et al. (2007). This approach and UAS-derived DEMs with centimeter and decimeter resolution are used, for example, for detailed analysis of glacier dynamics, glacier velocity, and studies of glacier drainage network (Whitehead et al., 2013; Immerzeel et al., 2014; Rippin et al., 2015; Ryan et al., 2015; Bhardwaj et al., 2016; Kraaijenbrink et al., 2016; Jouviet et al., 2017; Wigmore, Mark, 2017; Pogorelov et al., 2017; Bash et al., 2018; Petrakov et al., 2018). High resolution of such DEMs, in principle, enables research and modeling of glacial processes at the microtopographic scale.

2.2 Remaining Challenges

Despite the achievements, it is a non-trivial task to model glacier microtopography using high and very high resolution data from UAS surveys. This is mostly associated with physical properties of an ice/snow surface.

First, a UAS survey should be performed in sunny weather, or at variable and high cloudiness (Bliakharskii et al., 2019a). In this case, one can obtain contrast images with clearly visible, wind-created microtopographic ice/snow features. These microfeatures are used by correlation algorithms in searching tie points to construct a dense point cloud. It is highly undesirable to conduct a UAS survey under low cloudiness (and so diffuse lighting). In this case, one obtains low-contrast, whitish aerial images, with unrecognizable ice/snow microfeatures.

Second, glacier DEMs of a very high resolution can include myriads of high-frequency patterns, which represent not only microtopographic ice/snow features but also noise/artifacts. The latter are caused by both specificities of the formation of high-resolution images of the glistening ice/snow surface and photogrammetric processing of such aerial photographs. The geomorphometric maps derived from such DEMs are almost unreadable and so useless (Florinsky, Bliakharskii, 2019a). The problem is that it is impossible to suppress or remove correctly such noise and artifacts. This is because, in the case of a very high resolution glacier DEM, noise and signal levels can be comparable, so filtering may equally remove patterns of both the noise and signal.

Another unsolved problem of unmanned aerial survey of glaciers is the difficulty or impossibility to create and utilize a network of ground control points. This is due to safety reasons and restrictions (e.g., crevasse danger) as well as the continuous movement of the glacier surface. Application of the direct georeferencing approach (Chiang et al., 2012; Turner et al., 2014) can help solve this problem.

Over the past 20 years, progress has been made in the development of the theory and methods of digital terrain modeling and geomorphometry (Wilson, Gallant, 2000; Shary et al., 2002; Hengl, Reuter, 2009; Florinsky, 2016, 2017; Wilson, 2018). However, these advances have not yet been properly used in both processing of UAS-based data and glaciological studies.

3. AIM AND TASKS OF THE PROJECT

In spring 2020, we started a two-year, Russian–Chinese project to fill these gaps. The project is a continuation of our recent works (Florinsky et al., 2018; Florinsky, Bliakharskii, 2019a, 2019b; Bliakharskii, 2019; Bliakharskii et al., 2019a, 2019b, 2020).

The aim of the project is to develop a theory and methodology of mathematical modeling and analysis of glacier microtopography using UAS-derived data of high and ultra-high resolution. Among others, the following tasks are undertaken by the Russian side to achieve this objective:

1. To develop the theory of mathematical modeling of the glacier microtopography using UAS-derived data of high and ultra-high resolution.
2. To develop a computational geomorphometric method for crevasse detection based on UAS-derived data.
3. To develop a computational geomorphometric method for determining the horizontal and vertical velocity of the glacier flow based on multi-temporal, UAS-derived data using the direct georeferencing approach.
4. To carry out three-dimensional (3D) modeling of the glacier microtopography for the Larsemann Hills area, East Antarctica using UAS-derived aerial imagery of high and ultra-high resolution.
5. To test the developed theory and methods for analyzing the evolution of the glacier microtopography exemplified by the Larsemann Hills area.

4. STUDY AREA

The study was conducted at the ice sheet and glaciers near the Larsemann Hills, East Antarctica (Fig. 1). The Larsemann Hills are ice-free, low rounded hills with an area of about 40 km² located on the southeastern coast of the Prydz Bay, Princess Elizabeth Land (Stüwe et al. 1989). There are three year-round operated polar stations in this area: Progress (Russia), Zhongshan (China), and Bharati (India).

5. MATERIALS AND METHODS

5.1 UAS Survey

As initial data, we use multi-temporal, digital aerial images of a very high resolution (5 cm) collected by the unmanned aerial survey of the ice sheet and glaciers near the Larsemann Hills. The surveys were performed, inter alia, during the 62nd Russian Antarctic Expedition (December 2016 – February 2017) (Bliakharskii et al., 2019a).

In particular, we use data from the unmanned aerial survey of a portion of the sledge route from the Progress to Vostok Stations, from 69°27'24" S, 76°19'04" E to 69°40'40" S, 76°32'46" E (Bliakharskii et al., 2019a). The sledge route area had a length of ~30 km and a width of ~3 km. This area is a snow-covered ice sheet surface gradually rising to the south, from 284 m to 734 m above sea level.

The UAS survey of the sledge route area was conducted by Geoscan 201 Geodesy (Fig. 2), a professional-grade flying-wing UAS (Geoscan, 2016). The Geoscan 201 Geodesy was equipped with the following instruments:

1. A modem for communication with a laptop ground control station (as the ground GNSS base station, a receiver Topcon HiPer V was used).
2. A Topcon b110 GNSS receiver (GPS + GLONASS, L1 + L2).

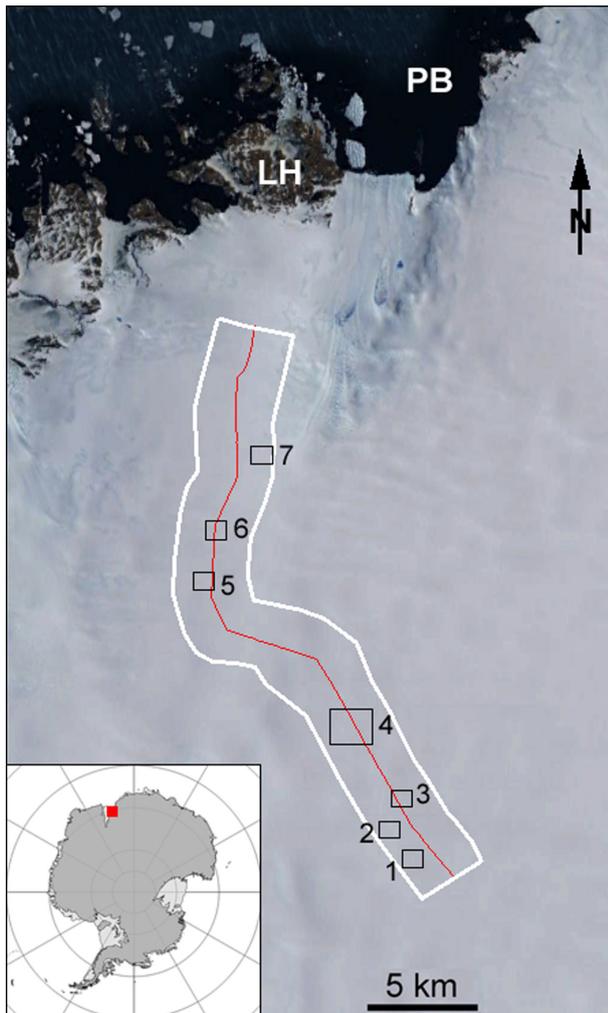


Figure 1. Geographical location of the surveyed area on the background of the U.S. Geological Survey image mosaic (from the Google Earth). The white frame — the area of the initial section of the sledge route (the red line) from the Progress to Vostok Stations. Black frames 1–7 — sites for studying microtopographic snow/ice features of eolian origin (see Figs. 4–8). LH — Larsemann Hills; PB — Prydz Bay



Figure 2. The Geoscan 201 Geodesy launching by a catapult at the study area

3. A field-calibrated, visible-band camera Sony DSC-RX1 with a Carl Zeiss Vario Sonnar T lens (a 35 mm focal length, a central leaf shutter) and a sensor (35.8mm × 23.9 mm, a 6,000 pixels × 4,000 pixels matrix with pixel sizes of 6 μm × 6 μm). The following settings for the camera were applied: (1) the lens was locked at infinity; (2) the shutter priority was at 1/1,000 s and 1/800 s for sunny and cloudy weather, correspondingly; (3) an aperture and ISO sensitivity were automatically selected per a flight strip.

The sledge route area was twice surveyed, in mid-January 2017 and early February 2017. During the first survey, the weather was good: there was sunny; the air temperature ranged from -5°C to -10°C; the wind speed was 10–15 m/s gusting up to 18–20 m/s at the flight altitude of 300–430 m. The wind was south katabatic in morning and north afternoon. The first survey consisted of 9 flights (195 flight strips including 9,381 images) for area of ~102 km². However, the weather deteriorated during the second survey: there was overcast with a cloud base of about 1000 m; the air temperature ranged from -7°C to -12°C; the wind speed was 15–20 m/s gusting up to 25–28 m/s at the flight altitude of 300–430 m. As a result, the second survey consisted of 5 flights (126 flight strips including 6,196 images) for the area of ~73 km².

The flights were performed using an autopilot at a constant altitude above ground level. Each flight took about 2 hrs. For all flights, forward and side overlaps were about 70% and 50%, correspondingly. Aerial images have an average resolution of 6 cm (Bliakharskii et al., 2019a).

5.2 Data Processing

To implement the direct georeferencing approach, we use Pinnacle 1.0, Trimble Business Center 2.0, and Magnet Office Tools 2.8 to process on-board GNSS receiver measurements and ground geodesic measurements. For processing UAS-derived imagery, we use software Agisoft PhotoScan Professional 1.3.2, Agisoft MetaShape Professional 1.5, and Photomod 6.0.

For the sledge route area, in particular, data treatment included the following key stages (Bliakharskii et al., 2019a):

1. Determination of the high-precision coordinates of image projection centers. This information was used for the post-processed kinematic direct georeferencing (Turner et al., 2014).
2. Alignment of images by the least-squares bundle adjustment using data from the camera field calibration. The aerial triangulation accuracy was as follows: planimetric X = 1.90 m, Y = 0.50 m; vertical H = 0.80 m.
3. Construction of a dense point cloud by the Agisoft semi-global matching algorithm.
4. Generation of a DEM applying triangulation and smooth interpolation of the dense point cloud.
5. Production of orthomosaics.

For the sledge route area, we produced two 1-m gridded DEMs related to mid-January 2017 and early February 2017 dates of the UAS surveys (Fig. 3). As horizontal and vertical datums, we applied WGS 1984 and EGM 2008, correspondingly.

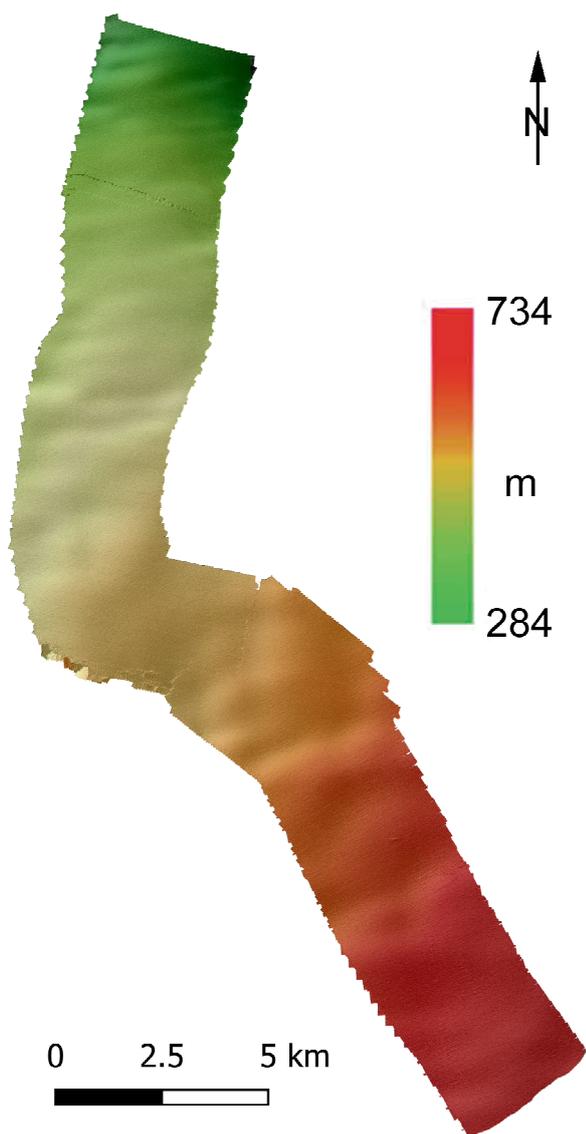


Figure 3. The area of the initial section of the sledge route from the Progress to Vostok Stations (the mid-January survey): the 1-m gridded hill-shaded elevation model

For geomorphometric calculation, 3D modeling, and visualization, we utilize the following software: LandLord 4.0 (Florinsky, 2016), MatLab R2008b, ArcMap 10.0, ENVI Classic 2.7, QGIS 3.00, and MapInfo Pro 16.0.1.

In particular, geomorphometric treatment of the data describing the sledge route area included derivation of high-resolution hill-shaded maps and construction of cross-sections (Figs. 4–8). These are used to study microtopographic snow/ice features of eolian origin, for example, elongated snow/ice patterns (which are, apparently, little *sastrugi*) stretching from southwest to northeast, perpendicular to the general local katabatic wind direction.

6. CONCLUSIONS

As a result of the ongoing project, we will develop a theory and methodology of geomorphometric modeling in the context of glaciological research in the Arctic, Antarctic, and highland regions.

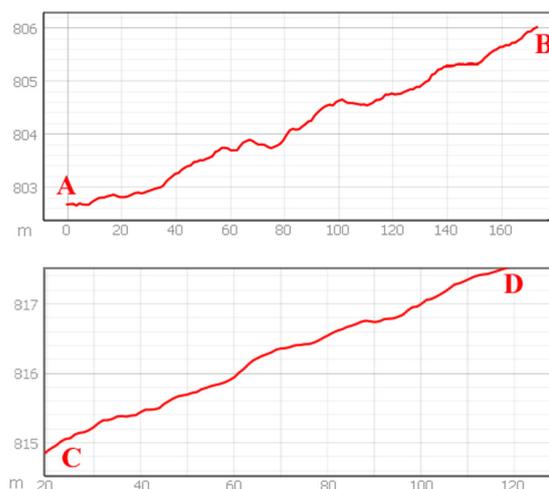
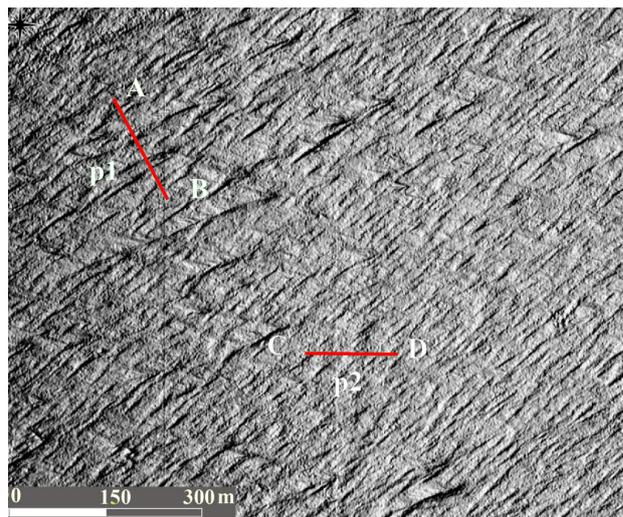


Figure 4. Microtopographic snow/ice features of eolian origin at the site 1: the 1-m gridded hill-shaded map and two cross-sections A–B and C–D. One can see snow/ice microfeatures of eolian origin. For the site location, see Fig. 1

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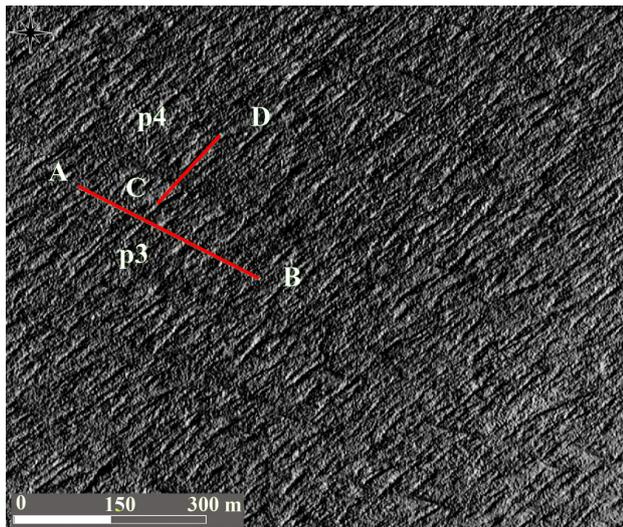


Figure 5. Microtopographic snow/ice features of eolian origin at the site 2: the 1-m gridded hill-shaded map and two cross-sections A–B and C–D. One can see snow/ice microfeatures of eolian origin. For the site location, see Fig. 1

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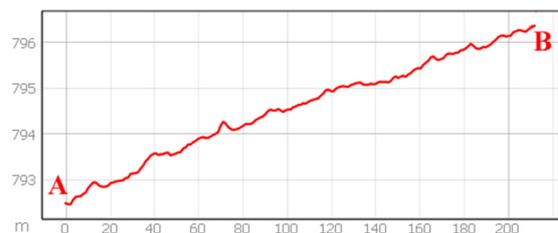
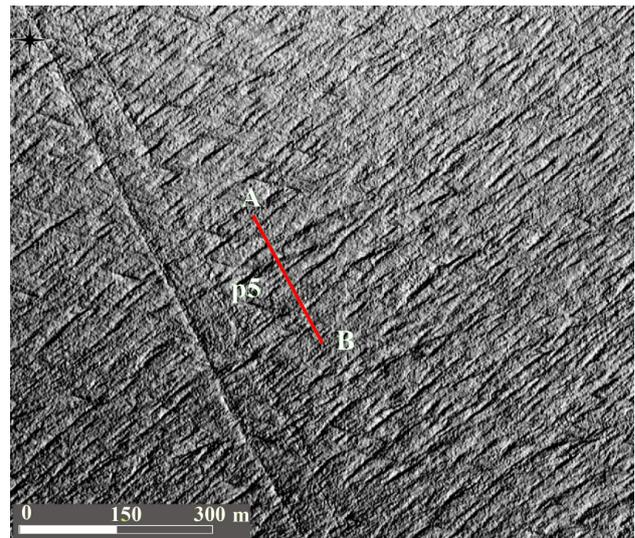


Figure 6. Microtopographic snow/ice features of eolian origin at the site 3: the 1-m gridded hill-shaded map and a cross-section A–B. One can see snow/ice microfeatures of eolian origin, as well as the sledge route crossing the site. For the site location, see Fig. 1

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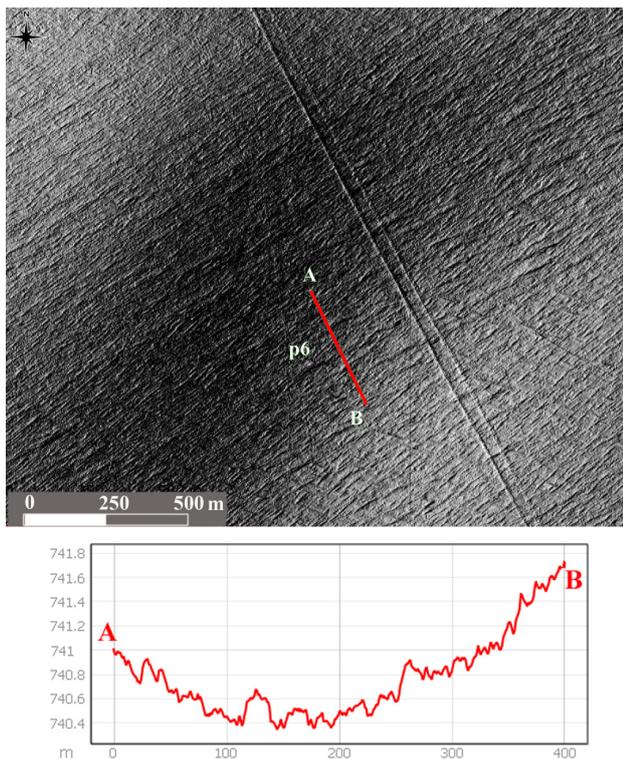


Figure 7. Microtopographic snow/ice features of eolian origin at the site 4: the 1-m gridded hill-shaded map and a cross-section A–B. One can see snow/ice microfeatures of eolian origin, as well as the sledge route crossing the site. For the site location, see Fig. 1

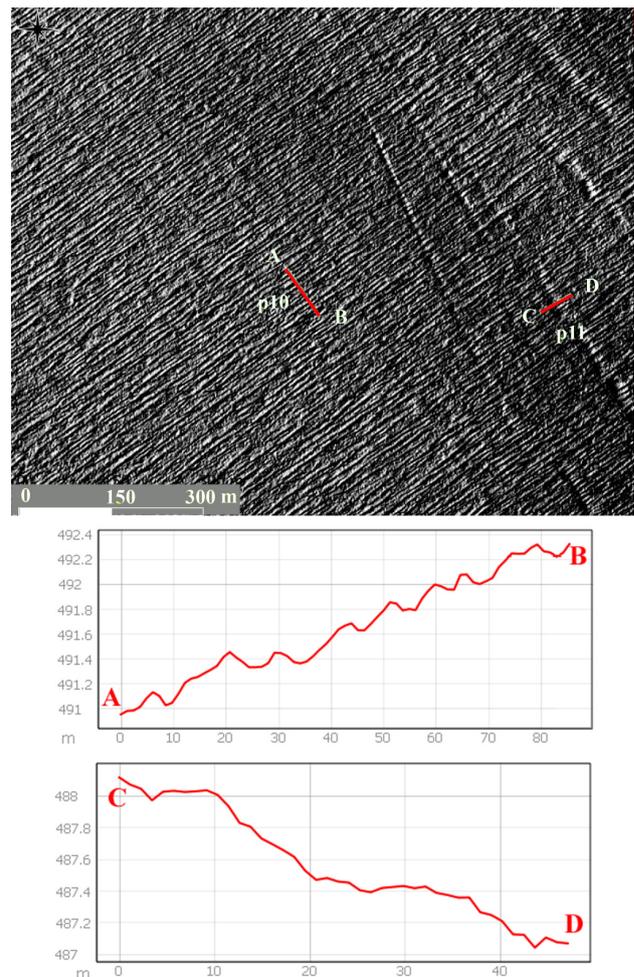


Figure 8. Microtopographic snow/ice features of eolian origin at the site 7: the 1-m gridded hill-shaded map and two cross-sections A–B and C–D. One can see snow/ice microfeatures of eolian origin, as well as several crevasses. For the site location, see Fig. 1

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