GENERATING HIGH-TEMPORAL AND SPATIAL RESOLUTION TIR IMAGE DATA

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Commission III, WG III/6

KEY WORDS: Data fusion, Image processing, Remote sensing, Thermal infrared data, Multisensor system, Spectral Unmixing.

ABSTRACT

Remote sensing imagery to monitor global biophysical dynamics requires the availability of thermal infrared data at high temporal and spatial resolution because of the rapid development of crops during the growing season and the fragmentation of most agricultural landscapes. Conversely, no single sensor meets these combined requirements. Data fusion approaches offer an alternative to exploit observations from multiple sensors, providing data sets with better properties. A novel spatio-temporal data fusion model based on constrained algorithms denoted as multisensor multisresolution technique (MMT) was developed and applied to generate TIR synthetic image data at both temporal and spatial high resolution. Firstly, an adaptive radiance model is applied based on spectral unmixing analysis of . TIR radiance data at TOA (top of atmosphere) collected by MODIS daily 1-km and Landsat – TIRS 16-day sampled at 30-m resolution are used to generate synthetic daily radiance images at TOA at 30-m spatial resolution. The next step consists of unmixing the 30 m (now lower resolution) images using the information about their pixel land-cover composition from co-registered images at higher spatial resolution. In our case study, TIR synthesized data were unmixed to the Sentinel 2 MSI with 10 m resolution. The constrained unmixing preserves all the available radiometric information of the 30 m images and involves the optimization of the number of land-cover classes and the size of the moving window for spatial unmixing. Results are still being evaluated, with particular attention for the quality of the data streams required to apply our approach.

1. INTRODUCTION

Thermal infrared (TIR) data is critical to model surface energy balance (Anderson et al., 2011), evapotranspiration and surface moisture (Carlson, 2007) and climate change (Weng, 2009). Biophysical variables and land-cover changes can be retrieved from radiometric data in this spectral region. Due to technical and financial constraints, no single sensor provides TIR data with both high spatial and temporal resolution (Price, 1994). Temporal characteristic are essential to detect rapid surface changes, decisive in crop-growth monitoring and intra-seasonal ecosystem disturbance (Shabanov et al., 2003). The spatial resolution is compulsory in detailed land-oriented applications to minimize the interpretation errors of the mixed pixels which may represent a mixture of different objects. Data-fusion models offer synthetic data integrating high spatial and temporal resolution from different sensors. It is a feasible and low-cost way to enhance the capability of remote sensing to monitor land surface dynamics. Thermal downscaling typically requires preserving the radiometry of original TIR radiance to quantitatively derive radiometry changes caused by phenology (Stathopoulou and Cartalis, 2009). The remote-sensing community has developed two well – documented approaches to do spatial and temporal data fusion. On one hand, the spatial and temporal adaptive reflectance fusion model (STARFM) proposed by Gao et al. (2006), in which daily Landsat synthetic data were generated from several pairs of Landsat and MODIS images on the same day and one MODIS image on the required day, using a weighted-average approach. On the other hand, existing spatial thermal sharpening techniques rely on disaggregating sensor radiance to higher resolutions usually supported by shorter wavebands, like visible and near-infrared (Dominguez et al., 2011), preserving the spectral configuration of coarse resolution data. These multisresolution image fusion techniques use various deterministic or statistical predictors (Zhukov and Oertel, 1996).

In this research, a new fusion algorithm to predict daily TIR data at 10-m resolution is developed. In the first step, Landsat 8/TIRS (Thermal Infrared Sensor) and MODIS data are blended to obtain daily TIR data at 30-m resolution. After that, the spatial resolution is improved to 10-m, taking advantages of the visible bands of Sentinel 2 MSI, based on a regularized spatial unmixing technique to reduce unmixing error among the mixed pixels. The paper is organized as follows: after this brief introduction, the proposed methodology is described. Next, the results and the discussion are presented. Finally, conclusions are drawn.

2. METHODOLOGY
The proposed approach was designed to generate high temporal and spatial resolution synthetic TIR data based on MMT algorithm. Figure 1 clarifies the workflow and the data products of our method, explained below.

\[ y(t) = a_0 + \sum_{i=1}^{nf} \left(a_i \cos(2\pi f_i t_y) + b_i \sin(2\pi f_i t_y) \right) \]

where \(nf\) is the number of frequencies, \(a_0\) is the average of the series and \(t_y\) the time of observation. The coefficients \(a\) and \(b\) are the coefficients of trigonometric components functions at the frequency \(f_i\).

After this correction, an unsupervised classification is used to identify pixels within the local moving window which are spectrally similar to the central pixel. Next, a weight function is applied that expresses the influence of neighbouring pixels on the central pixel. The weight function is adjusted to the location of the similar pixels and TIR radiance similarity between the fine and coarse resolution data. Finally, an extra-filter is applied to remove poor quality observations and to retain cloud-free pixels.

The next step consists of unmixing the 30-m (now lower resolution) TIR data using the information about their pixel land-cover composition from co-registered images at higher spatial resolution (Figure 2). In our study case, synthesized TIR data were un-mixed to the Sentinel 2 MSI 10 m resolution. Thereby, the MMT yields a high-resolution synthetic data at the required date. For this purpose, a classification map of the high resolution image through unsupervised algorithms (Zurita-Milla et al., 2008) is derived. The isodata algorithm is applied, which main contribution is that the number of cluster and their initial centroids do not need to be known. This algorithm was chosen among other unsupervised algorithms, such as k-means, with the aim at developing a more general
methodology, applicable to images independently of observed land cover, e.g. rural, urban, desert or forest areas. As an assumption, classes recognizable in the high-spatial resolution data, have the same spectral features in the central and surrounding pixels within the coarse resolution window. This constrained unmixing ensures that the emittance balance for the central pixel is met. A moving window processing can be applied to reduce the spatial scale of the within-class averaging to the selected window size. A window size of 5×5 pixels in the high-resolution image was found to be a good compromise between an acceptable spatial averaging scale of the coarse classes and a sufficient number of coarse pixels for a stable inversion (Zhukov et al., 1999). Then, the contributions of each cluster to the signal that falls within each Landsat-pixel inside the sliding window is evaluated. By combining the obtained proportion matrix and class spectra, the algorithm is used to downscale the coarse-resolution Landsat TIR data and retrieve more accurate spectral information for each cluster recognized in the high-resolution data. In order to preserve the available TIR radiometric information of the coarse resolution data, only the excess high spatial frequency components have to be transferred to the low-resolution bands. Finally, fused results at high spatial resolution are obtained by assigning the unmixed spectral information to each class by an inversion of a system of linear mixture equations to the fine resolution clustering map presented in the central pixel of the moving window (Xu et al., 2015).

![Figure 2. TIR image result at high spatial resolution](image)

3. EXPERIMENTAL RESULTS

The proposed approach was tested using the data set in the study area, covering 115 km × 100 km South-East of The Netherlands. The predominant wind direction in the Netherlands is southwest, which causes a moderate maritime climate with warm summers and cool winters and typically high humidity. It is a complex area covering many different land cover types, including farmland, forest, bare soil, urban land, wetlands and water as identified by the Netherlands Environmental Assessment Agency (PBL). Cropland patches are small and show distinct temporal patterns based on planting and harvest schedules and local environmental conditions such as soil water content, nutrition and health. In this context, monitoring this crop growth requires high spatial resolution imagery to isolate particular fields and high temporal resolution imagery to track development.

In this study, Landsat-8 level 1 T geotiff product (Band 10) at 30 m resolution and MODIS level-1 MOD021KM from collection 6 (Band 31) at 1 km resolution was employed. No time correction was applied for the sensor overpass time, choosing the MODIS acquisition time at 10:00 am, same time that Landsat-8 overpasses. This TIR dataset, used to model the estimator, was acquired for both sensors from 14th March 2016 and 20th July 2016. MODIS and Landsat data have to be geometrically pre-processed to the same pixel size and covering the same area and radiometrically calibrated, to ensure the radiance similar pixels. Furthermore, MODIS data was re-projected into Landsat WGS84 projection system by MODIS Reprojection Tools which use a bilinear resampling method. Moreover, a shared cloud mask was created for both Landsat and MODIS images to remove poor quality pixels, like cloudy areas, from the computation.

The date required for computation was 1st May; accordingly, MODIS image from this date was as well used. To generate the clustering map, Sentinel 2 MSI resolution data on the required date was used. In this step, a 5×5 pixel moving window for the unsupervised classification was chosen.

On this required date, there is a real TIR Landsat-8 image used to validate the proposed methodology. Figure 3 shows the reached result with the proposed methodology (figure 3a)) and the real TIR Landsat-8 image in radiance values. It worth noticed that the synthetic image is cloud-free, while the L8/ TIRS image includes a large cloud-covered area (light blue). The histogram of both image is illustrated in Figure 4, resampled to the same size. The mayor difference is due to the cloud values.

![Figure 3. Reached result with the proposed methodology](image)

![Figure 4. Histogram of both image](image)
ACKNOWLEDGMENT

The research is partly funded by “Smart irrigation from soil moisture forecast using satellite and hydro-meteorological modelling (SIM)” from the waterworks 2014 cofounded call. Authors would also like to thank the Government of Spain for funding given through human resources programmes (JCI-2015-24492 and CAS16/00060).

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Fig. 3. Synthetic high resolution TIR image (a) and existing TIR Landsat-8 (b) in radiance values from the same date.

Fig. 4. Histogram of the synthetic high resolution TIR image (in red) and the existing TIR Landsat-8 (in green) in radiance values.