







information obtained from UAV system, GPS, a gyroscope, an accelerometer, magnetic measuring sensor and other sensors, which allows the usage of real-time correction of UAV location through non-datum AT. From now on, acquisition of high resolution and high precision still images and DEM productions for evaluation part for accuracy of mapping, location of the UAV and position information and application methods for other non-datum aero triangulation methods need continuous studies. Selected comparably less windy day for the aerial photography using UAV,

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